## GENERALIZED ABRAHAM TRANSVERSALITY

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We use some of the notation from Section 11.2 on transversality. Assume that  $\mathscr{A}$  is a topological space and manifolds M and N. The map  $\rho : \mathscr{A} \to C^r(M, N)$  is called a  $C^r$  pseudo-representation provided that both  $\rho$  and  $\rho^{\text{ev}} : \mathscr{A} \times M \to N$  that is defined by  $\rho^{\text{ev}}(f, \mathbf{x}) = \rho(f)(\mathbf{x})$  are continuous.

**Theorem 1.** Let M and N be finite dimensional second countable manifolds, K a compact subset of M a compact subset, and  $V \subset N$  a closed  $C^1$  submanifold of N. Assume that  $\rho : \mathscr{A} \to C^r(M, N)$  is a  $C^1$  pseudo-representation with  $r \geq 1$ , and let

 $\mathscr{R} = \{ f \in \mathscr{A} : \rho(f) \text{ is transverse to } V \}.$ 

- **a.** Then the subset  $\mathscr{R}$  is an open subset of  $\mathscr{A}$ .
- **b.** If  $\rho : \mathscr{A} \to C^r(M, N)$  is a  $C^r$  pseudo-representation with  $r \ge \max\{1, 1 + \dim(M) \operatorname{codim}(V)\}$  and  $\rho^{ev}$  is transverse to V, then  $\mathscr{R}$  is residual in  $\mathscr{A}$  and hence dense.

The proof of part  $(\mathbf{a})$  is basically the same as the openness in [1].

The most important assumption for part (b) is that  $\rho^{\text{ev}}$  is transverse to V. This assumption means that if  $\rho(f)(\mathbf{x}) \in V$ , then the space  $\mathscr{A}$  of functions is large enough to be able to perturb f to be transverse to V at  $\mathbf{x}$ . The theorem then globalizes this result to give a perturbation that is transverse to V at all points of K. M. Hirsch communicated this version of the Abraham transversality theorem in a course in 1967. Unfortunately, his book [2] does not contain this general version. The proof uses the form of the Parametric transversality Theorem XI.2.3, and the compactness of K. The details are given in [3].

## References

- [1] R. Abraham and J. Robbin (1967), Transversal Mappings and Flows, Benjamin, New York.
- [2] M. Hirsch (1976), Differential Topology, Springer-Verlag, New York.

<sup>[3]</sup> C. Robinson (1970), A global approximation theorem for Hamiltonian systems, in Proc. Symposia in Pure Math. of the Amer. Math. Soc., (eds. S. S. Chern and S. Smale), Amer. Math. Soc., 14, pp. 233–243.