Best and random approximation of convex bodies by polytopes

・ロト・日本・モト・モート ヨー うへで

a convex body K in \mathbb{R}^n is compact convex set with non-empty interior

a polytope P in \mathbb{R}^n is the convex hull of finitely many points x_1,\ldots,x_N

 $[x_1,\ldots,x_N]$

a convex body K in \mathbb{R}^n is compact convex set with non-empty interior

a polytope *P* in \mathbb{R}^n is the convex hull of finitely many points x_1, \ldots, x_N

 $[x_1,\ldots,x_N]$

How well can a convex body be approximated by a polytope?

- 1. Approximation by a polytope P with
- (i) a fixed number of vertices
- (ii) a fixed number of facets = (n 1)-dimensional faces

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

(iii) a fixed number of k-dimensional faces

- 1. Approximation by a polytope P with
- (i) a fixed number of vertices
- (ii) a fixed number of facets = (n-1)-dimensional faces

- (iii) a fixed number of k-dimensional faces
- We will mostly concentrate on (i), the vertex case

- 1. Approximation by a polytope P with
- (i) a fixed number of vertices
- (ii) a fixed number of facets = (n 1)-dimensional faces

- (iii) a fixed number of k-dimensional faces
- We will mostly concentrate on (i), the vertex case

Typically, in the literature

- in (i) P is inscribed in K
- in (ii) P is circumscribed to K

2. Approximated in which sense ?

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

2. Approximated in which sense ?

(i) The symmetric difference metric

$$\Delta_{\nu}(K,L) = \operatorname{vol}_{n}\left((K \setminus L) \cup (L \setminus K)\right) = |(K \setminus L) \cup (L \setminus K)|$$
$$= |K \cup L| - |K \cap L|$$

2. Approximated in which sense ?

(i) The symmetric difference metric

$$\Delta_{\nu}(K,L) = \operatorname{vol}_{n}\left((K \setminus L) \cup (L \setminus K)\right) = |(K \setminus L) \cup (L \setminus K)|$$
$$= |K \cup L| - |K \cap L|$$

When $K \subset L$,

$$\Delta_v(K,L) = |L| - |K|$$

• the convex body K

- \bullet the convex body K
- the dimension n

- the convex body K
- the dimension n

when the number of vertices of the approximating polytope is $\ensuremath{\mathsf{prescribed}}$

- the convex body K
- the dimension *n*

when the number of vertices of the approximating polytope is prescribed

or the number of facets of the approximating polytope is prescribed

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

- the convex body K
- the dimension *n*

when the number of vertices of the approximating polytope is prescribed

or the number of facets of the approximating polytope is prescribed

• we want the optimal dependence on the number of vertices, of facets, etc....

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

- the convex body K
- the dimension n

when the number of vertices of the approximating polytope is prescribed

or the number of facets of the approximating polytope is prescribed

• we want the optimal dependence on the number of vertices, of facets, etc....

BEST APPROXIMATION

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Suppose K has a C²-boundary with everywhere positive Gauss curvature κ . Then

・ロト・日本・モト・モート ヨー うへで

Suppose K has a C²-boundary with everywhere positive Gauss curvature $\kappa.$ Then

 $\lim_{N \to \infty} \frac{\inf \{\Delta_{\nu}(K, P_N) | P_N \subset K \text{ and } P_N \text{ has at most N vertices}\}}{\frac{1}{N^{\frac{2}{n-1}}}}$

・ロト・日本・モート モー うへぐ

Suppose K has a C²-boundary with everywhere positive Gauss curvature κ . Then

 $\lim_{N \to \infty} \frac{\inf \{\Delta_{\nu}(K, P_N) | P_N \subset K \text{ and } P_N \text{ has at most N vertices}\}}{\frac{1}{N^{\frac{2}{n-1}}}}$

 $= \lim_{N \to \infty} \frac{\inf\{|K| - |P_N|: P_N \subset K \text{ and } P_N \text{ has at most N vertices}\}}{\frac{1}{N^{\frac{2}{n-1}}}}$

Suppose K has a C²-boundary with everywhere positive Gauss curvature κ . Then

 $\lim_{N \to \infty} \frac{\inf \{\Delta_{\nu}(K, P_N) | P_N \subset K \text{ and } P_N \text{ has at most N vertices}\}}{\frac{1}{N^{\frac{2}{n-1}}}}$

 $= \lim_{N \to \infty} \frac{\inf\{|K| - |P_N| : P_N \subset K \text{ and } P_N \text{ has at most N vertices}\}}{\frac{1}{N^{\frac{2}{n-1}}}}$ $= \frac{1}{2} \operatorname{del}_{n-1} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x) \right)^{\frac{n+1}{n-1}}$

 μ is the surface area measure on ∂K

Suppose K has a C²-boundary with everywhere positive Gauss curvature κ . Then

 $\lim_{N \to \infty} \frac{\inf \{\Delta_{\nu}(K, P_N) | \ P_N \subset K \text{ and } P_N \ \text{has at most N vertices}\}}{\frac{1}{N^{\frac{2}{n-1}}}}$

 $= \lim_{N \to \infty} \frac{\inf\{|K| - |P_N| : P_N \subset K \text{ and } P_N \text{ has at most N vertices}\}}{\frac{1}{N^{\frac{2}{n-1}}}}$ $= \frac{1}{2} \operatorname{del}_{n-1} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x) \right)^{\frac{n+1}{n-1}}$

(日) (同) (三) (三) (三) (○) (○)

 μ is the surface area measure on ∂K del_{*n*-1} is a constant that depends only on *n*

$$\begin{array}{lll} \Delta_{\nu}(K,P_{\text{best}}) & = & |K| - |P_{\text{best}}| \\ & \sim & \displaystyle \frac{1}{2} \text{del}_{n-1} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x) \right)^{\frac{n+1}{n-1}} \frac{1}{N^{\frac{2}{n-1}}} \end{array}$$

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

$$\begin{array}{lll} \Delta_{\nu}(K,P_{\text{best}}) & = & |K| - |P_{\text{best}}| \\ & \sim & \frac{1}{2} \mathsf{del}_{n-1} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x) \right)^{\frac{n+1}{n-1}} \frac{1}{N^{\frac{2}{n-1}}} \end{array}$$

Theorem (Mankiewicz&Schütt)

There is a numerical constant c > 0 such that

$$\frac{n-1}{n+1} \left(\frac{1}{|B_2^{n-1}|}\right)^{\frac{2}{n-1}} \leq \mathsf{del}_{n-1} \leq \left(1 + \frac{c \log n}{n}\right) \frac{n-1}{n+1} \left(\frac{1}{|B_2^{n-1}|}\right)^{\frac{2}{n-1}}$$

$$\begin{array}{lll} \Delta_{\nu}(K,P_{\text{best}}) & = & |K| - |P_{\text{best}}| \\ & \sim & \frac{1}{2} \mathsf{del}_{n-1} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x) \right)^{\frac{n+1}{n-1}} \frac{1}{N^{\frac{2}{n-1}}} \end{array}$$

Theorem (Mankiewicz&Schütt)

There is a numerical constant c > 0 such that

$$\frac{n-1}{n+1} \left(\frac{1}{|B_2^{n-1}|}\right)^{\frac{2}{n-1}} \le \det_{n-1} \le \left(1 + \frac{c \log n}{n}\right) \frac{n-1}{n+1} \left(\frac{1}{|B_2^{n-1}|}\right)^{\frac{2}{n-1}} \det_{n-1} \sim n$$

$$\begin{array}{lll} \Delta_{\nu}(\mathcal{K}, \mathcal{P}_{\mathsf{best}}) &=& |\mathcal{K}| - |\mathcal{P}_{\mathsf{best}}| \\ &\sim& \frac{1}{2} \mathsf{del}_{n-1} \left(\int_{\partial \mathcal{K}} \kappa(x)^{\frac{1}{n+1}} d\mu(x) \right)^{\frac{n+1}{n-1}} \frac{1}{N^{\frac{2}{n-1}}} \end{array}$$

Theorem (Mankiewicz&Schütt)

There is a numerical constant c > 0 such that

$$\frac{n-1}{n+1} \left(\frac{1}{|B_2^{n-1}|}\right)^{\frac{2}{n-1}} \le \det_{n-1} \le \left(1 + \frac{c \log n}{n}\right) \frac{n-1}{n+1} \left(\frac{1}{|B_2^{n-1}|}\right)^{\frac{2}{n-1}} \det_{n-1} \sim n$$

Affine surface area appears

$$as(K) = \int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x)$$

Random approximation

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

Choose *N* points $x_1 \dots x_N$ in *K* or on ∂K w.r. to a probability measure \mathbb{P} ,

Choose *N* points $x_1 \ldots x_N$ in *K* or on ∂K w.r. to a probability measure \mathbb{P} ,

$$\mathbb{P} = \frac{m}{|K|}$$
 or $\mathbb{P} = \frac{\mu}{|\partial K|}$

Random approximation

Choose *N* points $x_1 \ldots x_N$ in *K* or on ∂K w.r. to a probability measure \mathbb{P} ,

$$\mathbb{P} = rac{m}{|\mathcal{K}|}$$
 or $\mathbb{P} = rac{\mu}{|\partial \mathcal{K}|}$

the convex hull $[x_1, \ldots, x_N]$ of these points we call

RANDOM POLYTOPE

Random approximation

Choose *N* points $x_1 \ldots x_N$ in *K* or on ∂K w.r. to a probability measure \mathbb{P} ,

$$\mathbb{P} = rac{m}{|\mathcal{K}|}$$
 or $\mathbb{P} = rac{\mu}{|\partial \mathcal{K}|}$

the convex hull $[x_1, \ldots, x_N]$ of these points we call

RANDOM POLYTOPE

when chosen in K, not ALL points become vertices



< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

More generally:

 $f:\partial K o \mathbb{R}^+$ strictly positive a.e. on ∂K , $\int_{\partial K} f d\mu = 1$

$$\mathbb{P}_f = f \mu$$

<□ > < @ > < E > < E > E のQ @

More generally:

 $f:\partial K o \mathbb{R}^+$ strictly positive a.e. on ∂K , $\int_{\partial K} f d\mu = 1$

$$\mathbb{P}_f = f \mu$$

Choose N points $x_1, \ldots x_N$ w.r. to \mathbb{P}_f on ∂K

As before we call their convex hull $[x_1, \ldots, x_N]$ a **random polytope**. **Every** point chosen becomes a vertex



・ロット (日) (日) (日) (日) (日)

The expected volume of such a random polytope is

$$\mathbb{E}_{N}(\partial K, \mathbb{P}_{f}) = \int_{\partial K} \cdots \int_{\partial K} \left| [x_{1}, \ldots, x_{N}] \right| d\mathbb{P}_{f}(x_{1}) \ldots d\mathbb{P}_{f}(x_{N})$$

Theorem (Schütt&Werner)

Let K be a convex body in \mathbb{R}^n with sufficiently regular boundary.

(ロ)、(型)、(E)、(E)、 E) の(の)

$$\lim_{N\to\infty}\frac{|K| - \mathbb{E}_N(\partial K, \mathbb{P}_f)}{\left(\frac{1}{N}\right)^{\frac{2}{n-1}}} =$$

Theorem (Schütt&Werner)

Let K be a convex body in \mathbb{R}^n with sufficiently regular boundary.

$$\lim_{N\to\infty}\frac{|K|-\mathbb{E}_N(\partial K,\mathbb{P}_f)}{\left(\frac{1}{N}\right)^{\frac{2}{n-1}}} = c_n \int_{\partial K}\frac{\kappa(x)^{\frac{1}{n-1}}}{f(x)^{\frac{2}{n-1}}}d\mu(x)$$

(ロ)、(型)、(E)、(E)、 E) の(の)

Theorem (Schütt&Werner)

Let K be a convex body in \mathbb{R}^n with sufficiently regular boundary.

$$\lim_{N\to\infty}\frac{|K| - \mathbb{E}_N(\partial K, \mathbb{P}_f)}{\left(\frac{1}{N}\right)^{\frac{2}{n-1}}} = c_n \int_{\partial K} \frac{\kappa(x)^{\frac{1}{n-1}}}{f(x)^{\frac{2}{n-1}}} d\mu(x)$$

▶ when points are chosen in *K*, one only gets:

$$\left(\frac{1}{N}\right)^{\frac{2}{n+1}}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ
Theorem (Schütt&Werner)

►

Let K be a convex body in \mathbb{R}^n with sufficiently regular boundary.

$$\lim_{N\to\infty}\frac{|K| - \mathbb{E}_N(\partial K, \mathbb{P}_f)}{\left(\frac{1}{N}\right)^{\frac{2}{n-1}}} = c_n \int_{\partial K} \frac{\kappa(x)^{\frac{1}{n-1}}}{f(x)^{\frac{2}{n-1}}} d\mu(x)$$

▶ when points are chosen in *K*, one only gets:

$$\left(\frac{1}{N}\right)^{\frac{2}{n+1}}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

$$c_n = \frac{(n-1)^{\frac{n+1}{n-1}}\Gamma\left(n+1+\frac{2}{n-1}\right)}{2(n+1)!(\operatorname{vol}_{n-2}(\partial B_2^{n-1}))^{\frac{2}{n-1}}}$$

• the geometric tool we use is a variant of the (convex) **floating body** (Schütt+Werner):

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

• the geometric tool we use is a variant of the (convex) **floating body** (Schütt+Werner):

Let K be a convex body in \mathbb{R}^n . Let $\delta > 0$. The (convex) **floating body** is the intersection of all halfspaces H^+ whose defining hyperplanes H cut off a set of volume δ of K.



• the geometric tool we use is a variant of the (convex) **floating body** (Schütt+Werner):

Let K be a convex body in \mathbb{R}^n . Let $\delta > 0$. The (convex) **floating body** is the intersection of all halfspaces H^+ whose defining hyperplanes H cut off a set of volume δ of K.



$$|\mathcal{K}| - \mathbb{E}_N(\partial \mathcal{K}, \mathbb{P}_f) \sim c_n \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \int_{\partial \mathcal{K}} \frac{\kappa(x)^{\frac{1}{n-1}}}{f(x)^{\frac{2}{n-1}}} d\mu(x)$$

▲□▶ ▲□▶ ▲三▶ ▲三▶ ▲□ ● ● ●

$$|\mathcal{K}| - \mathbb{E}_{N}(\partial \mathcal{K}, \mathbb{P}_{f}) \sim c_{n} \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \int_{\partial \mathcal{K}} \frac{\kappa(x)^{\frac{1}{n-1}}}{f(x)^{\frac{2}{n-1}}} d\mu(x)$$

▶ the optimal *f* which minimizes the right hand side is

$$f_{as} = \frac{\kappa^{\frac{1}{n+1}}}{\int_{\partial K} \kappa^{\frac{1}{n+1}} d\mu}$$

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

$$|\mathcal{K}| - \mathbb{E}_N(\partial \mathcal{K}, \mathbb{P}_f) \sim c_n \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \int_{\partial \mathcal{K}} \frac{\kappa(x)^{\frac{1}{n-1}}}{f(x)^{\frac{2}{n-1}}} d\mu(x)$$

the optimal f which minimizes the right hand side is

$$f_{as} = \frac{\kappa^{\frac{1}{n+1}}}{\int_{\partial K} \kappa^{\frac{1}{n+1}} d\mu}$$

Putting this f_{as} in the above formula, we get

$$|\mathcal{K}| - \mathbb{E}_N(\partial \mathcal{K}, \mathbb{P}_f) \sim c_n \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \int_{\partial \mathcal{K}} \frac{\kappa(x)^{\frac{1}{n-1}}}{f(x)^{\frac{2}{n-1}}} d\mu(x)$$

the optimal f which minimizes the right hand side is

$$f_{as} = \frac{\kappa^{\frac{1}{n+1}}}{\int_{\partial K} \kappa^{\frac{1}{n+1}} d\mu}$$

Putting this f_{as} in the above formula, we get

$$\blacktriangleright |K| - \mathbb{E}_{N}(\partial K, \mathbb{P}_{f_{as}}) \sim c_{n} \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x)\right)^{\frac{n+1}{n-1}}$$

$$|\mathcal{K}| - \mathbb{E}_N(\partial \mathcal{K}, \mathbb{P}_f) \sim c_n \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \int_{\partial \mathcal{K}} \frac{\kappa(x)^{\frac{1}{n-1}}}{f(x)^{\frac{2}{n-1}}} d\mu(x)$$

the optimal f which minimizes the right hand side is

$$f_{as} = \frac{\kappa^{\frac{1}{n+1}}}{\int_{\partial K} \kappa^{\frac{1}{n+1}} d\mu}$$

Putting this f_{as} in the above formula, we get

$$\blacktriangleright |K| - \mathbb{E}_{N}(\partial K, \mathbb{P}_{f_{as}}) \sim c_{n} \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x)\right)^{\frac{n+1}{n-1}}$$

How do best and random approximation compare?

$$|K| - |P_{\text{best}}| \sim \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x)\right)^{\frac{n+1}{n-1}} \frac{1}{2} \text{del}_{n-1} |K| - \mathbb{E}_N(\partial K, \mathbb{P}_{f_{as}}) \sim \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x)\right)^{\frac{n+1}{n-1}} c_n$$

▲□▶ ▲□▶ ▲三▶ ▲三▶ ▲□ ● ● ●

$$|K| - |P_{\text{best}}| \sim \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x)\right)^{\frac{n+1}{n-1}} \frac{1}{2} \text{del}_{n-1} |K| - \mathbb{E}_N(\partial K, \mathbb{P}_{f_{as}}) \sim \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x)\right)^{\frac{n+1}{n-1}} c_n$$

To see how best and random approximation compare, we have to compare c_n and $\frac{1}{2}$ del_{n-1}

$$|K| - |P_{\text{best}}| \sim \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x)\right)^{\frac{n+1}{n-1}} \frac{1}{2} \text{del}_{n-1} |K| - \mathbb{E}_N(\partial K, \mathbb{P}_{f_{as}}) \sim \left(\frac{1}{N}\right)^{\frac{2}{n-1}} \left(\int_{\partial K} \kappa(x)^{\frac{1}{n+1}} d\mu(x)\right)^{\frac{n+1}{n-1}} c_n$$

To see how best and random approximation compare, we have to compare c_n and $\frac{1}{2}$ del_{n-1}

With an absolute constant c

$$\frac{1}{2} \operatorname{del}_{n-1} \leq c_n \leq \left(1 + \frac{c \log n}{n}\right) \frac{1}{2} \operatorname{del}_{n-1}$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

1. Approximation by a polytope P with

- (i) a fixed number of vertices
- (ii) a fixed number of facets = (n-1)-dimensional faces

1. Approximation by a polytope P with

- (i) a fixed number of vertices
- (ii) a fixed number of facets = (n 1)-dimensional faces

Typically, in the literature

- in (i) P is inscribed in K
- in (ii) P is circumscribed to K

1. Approximation by a polytope P with

- (i) a fixed number of vertices
- (ii) a fixed number of facets = (n 1)-dimensional faces

Typically, in the literature

in (i) P is inscribed in K

in (ii) P is circumscribed to K

These restrictions need to be dropped

Again: we concentrate on the vertex case

◆□ > ◆□ > ◆臣 > ◆臣 > ○臣 ○ のへで

Theorem (Ludwig, Schütt, Werner)

Let K be C^2_+ . There is a constant c > 0 s.th. for all $n \in \mathbb{N}$ there is $N_n \in \mathbb{N}$ s.th. for all $N \ge N_n$ there is a polytope P in \mathbb{R}^n with at most N vertices s.th.

$$\Delta_{v}(K,P) \leq c |K| \left(rac{1}{N}
ight)^{rac{2}{n-1}}$$

Theorem (Ludwig, Schütt, Werner)

Let K be C^2_+ . There is a constant c > 0 s.th. for all $n \in \mathbb{N}$ there is $N_n \in \mathbb{N}$ s.th. for all $N \ge N_n$ there is a polytope P in \mathbb{R}^n with at most N vertices s.th.

$$\Delta_{v}(K,P) \leq c |K| \left(\frac{1}{N}\right)^{\frac{2}{n-1}}$$

the corresponding result for facets holds as well

Theorem (Ludwig, Schütt, Werner)

Let K be C^2_+ . There is a constant c > 0 s.th. for all $n \in \mathbb{N}$ there is $N_n \in \mathbb{N}$ s.th. for all $N \ge N_n$ there is a polytope P in \mathbb{R}^n with at most N vertices s.th.

$$\Delta_{v}(K,P) \leq c |K| \left(\frac{1}{N}\right)^{\frac{2}{n-1}}$$

- the corresponding result for facets holds as well
- When $P \subset K$ (Bronsteyn&Ivanov)

$$\Delta_{v}(K,P) = |K| - |P| \leq c \ n \ |K| \ \left(\frac{1}{N}\right)^{\frac{2}{n-1}}$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Theorem (Ludwig, Schütt, Werner)

Let K be C^2_+ . There is a constant c > 0 s.th. for all $n \in \mathbb{N}$ there is $N_n \in \mathbb{N}$ s.th. for all $N \ge N_n$ there is a polytope P in \mathbb{R}^n with at most N vertices s.th.

$$\Delta_{v}(K,P) \leq c |K| \left(\frac{1}{N}\right)^{\frac{2}{n-1}}$$

- the corresponding result for facets holds as well
- When $P \subset K$ (Bronsteyn&lvanov)

$$\Delta_{v}(K,P) = |K| - |P| \le c \ n \ |K| \ \left(\frac{1}{N}\right)^{\frac{2}{n-1}}$$

• If we drop the restriction, we gain by a factor of dimension: n

Theorem (Böröczky)

For every polytope P_N with at most N vertices

$$\Delta_{\nu}(B_2^n,P_N)| \geq \frac{c}{n} \left(\frac{1}{N}\right)^{\frac{2}{n-1}} |B_2^n|$$

・ロト・日本・モト・モート ヨー うへで

Theorem (Böröczky)

For every polytope P_N with at most N vertices

$$\Delta_{\mathbf{v}}(B_2^n,P_N)| \geq \frac{c}{n} \left(\frac{1}{N}\right)^{\frac{2}{n-1}} |B_2^n|$$

RECALL upper bound

$$\Delta_{v}(B_{2}^{n},P)\leq c~\left(rac{1}{N}
ight)^{rac{2}{n-1}}~|B_{2}^{n}|$$

Theorem (Böröczky)

For every polytope P_N with at most N vertices

$$\Delta_{\mathbf{v}}(B_2^n,P_N)| \geq \frac{c}{n} \left(\frac{1}{N}\right)^{\frac{2}{n-1}} |B_2^n|$$

RECALL upper bound

$$\Delta_{v}(B_{2}^{n},P)\leq c~\left(rac{1}{N}
ight)^{rac{2}{n-1}}~|B_{2}^{n}|$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□▶

GAP between lower and upper bound by a factor of dimension

2. Approximated in which sense

(i) The symmetric difference metric

$$\Delta_{v}(K,L) = |K \cup L| - |K \cap L|$$

2. Approximated in which sense

(i) The symmetric difference metric

$$\Delta_{v}(K,L) = |K \cup L| - |K \cap L|$$

(ii) The surface deviation

$$\Delta_{s}(K,L) = \operatorname{vol}_{n-1} \left(\partial(K \cup L) \right) - \operatorname{vol}_{n-1} \left(\partial(K \cap L) \right)$$

= $\left| \partial(K \cup L) \right| - \left| \partial(K \cap L) \right|$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

2. Approximated in which sense

(i) The symmetric difference metric

$$\Delta_{v}(K,L) = |K \cup L| - |K \cap L|$$

(ii) The surface deviation

$$\Delta_{s}(K,L) = \operatorname{vol}_{n-1} \left(\partial(K \cup L) \right) - \operatorname{vol}_{n-1} \left(\partial(K \cap L) \right)$$

= $\left| \partial(K \cup L) \right| - \left| \partial(K \cap L) \right|$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

• Δ_s is not a metric: it fails the triangle inequality

There are many other metrics (Hausdorff, ...). The advantage of the above: those are Quermassintegrals

There are many other metrics (Hausdorff, ...). The advantage of the above: those are Quermassintegrals

$$1 \leq \lim_{N \to \infty} \frac{\mathbb{E}_N \left(\Delta_v(K, P_{\mathbb{P}_f}) \right)}{\Delta_v(K, P_{\mathsf{best}})} \leq 1 + c \ \frac{\log n}{n}$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

<ロ> <昂> < 言> < 言> < 言> < こ> < のへの</p>

Surface deviation

Theorem (Hoehner, Schütt & Werner)

There exists an absolute constant c > 0 such that for every integer $n \ge 3$, there is an N_n such that for every $N \ge N_n$ there is a polytope P_N in \mathbb{R}^n with N vertices such that

$$\Delta_s(B_2^n,P_N) \leq c \, rac{\operatorname{\mathsf{vol}}_{n-1}\left(\partial B_2^n
ight)}{N^{rac{2}{n-1}}}$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Surface deviation

Theorem (Hoehner, Schütt & Werner)

There exists an absolute constant c > 0 such that for every integer $n \ge 3$, there is an N_n such that for every $N \ge N_n$ there is a polytope P_N in \mathbb{R}^n with N vertices such that

$$\Delta_s(B_2^n, P_N) \leq c \frac{\operatorname{vol}_{n-1}(\partial B_2^n)}{N^{\frac{2}{n-1}}}$$

▶ We gain by a factor of dimension when we drop the assumption that the polytope is contained in K

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Surface deviation

Theorem (Hoehner, Schütt & Werner)

There exists an absolute constant c > 0 such that for every integer $n \geq 3$, there is an N_n such that for every $N \geq N_n$ there is a polytope P_N in \mathbb{R}^n with N vertices such that

$$\Delta_s(B_2^n, P_N) \leq c \, \frac{\operatorname{vol}_{n-1}\left(\partial B_2^n\right)}{N^{\frac{2}{n-1}}}$$

We gain by a factor of dimension when we drop the assumption that the polytope is contained in K

Theorem (J. Müller)

Let P_N be the convex hull of N points chosen i.i.d. from ∂B_2^n with respect to the normalized surface measure. Then for N large

$$\operatorname{vol}_{n-1}(\partial B_2^n) - \mathbb{E}\operatorname{vol}_{n-1}(\partial P_N) \sim n \frac{\operatorname{vol}_{n-1}(\partial B_2^n)}{N^{\frac{2}{n-1}}}$$

A polytope in ℝⁿ is called simple if at every vertex exactly n facets meet.
A polytope in ℝⁿ is called simple if at every vertex exactly n facets meet.

Proposition (Hoehner, Schütt & Werner)

There is a constant c > 0 and $N_0 \in \mathbb{N}$ such that for all $n \in \mathbb{N}$ with $n \ge 2$, all $N \in \mathbb{N}$ with $N \ge N_0$ and all **simple** polytopes P_N in \mathbb{R}^n with no more than N vertices

$$\Delta_s(B_2^n, P_N) \geq c rac{\mathrm{vol}_{\mathrm{n}-1}(\partial \mathrm{B}_2^\mathrm{n})}{N^{rac{2}{n-1}}}.$$

Theorem (Hoehner, Schütt, Werner)

There exists an absolute constant c > 0 such that for every integer $n \ge 3$, there is an N_n such that for every $N \ge N_n$ there is a polytope P_N in \mathbb{R}^n with N vertices such that

$$\Delta_s(B_2^n, P_N) \leq c \, rac{\operatorname{vol}_{n-1}\left(\partial B_2^n
ight)}{N^{rac{2}{n-1}}}$$

We choose at random points x_1, \ldots, x_N with respect to $\mathbb{P} = \frac{\mu_{\partial B_2^n}}{|\partial B_2^n|}$ on ∂B_2^n . Get random polytope

$$P_N = [x_1, \ldots, x_N]$$

We choose at random points x_1, \ldots, x_N with respect to $\mathbb{P} = \frac{\mu_{\partial B_2^n}}{|\partial B_2^n|}$ on ∂B_2^n . Get random polytope

$$P_N = [x_1, \ldots, x_N]$$

We choose the points from ∂B_2^n and we approximate

 $(1-r)B_2^n$, r chosen appropriately

We want to estimate

$$\mathbb{E}[\Delta_s((1-r)B_2^n, P_N)] = \int_{\partial B_2^n} \cdots \int_{\partial B_2^n} \left| \partial((1-r)B_2^n \cup [x_1, \dots, x_N]) \right| - \left| \partial((1-r)B_2^n \cap [x_1, \dots, x_N]) \right| d\mathbb{P}(x_1) \dots d\mathbb{P}(x_N)$$

We want to estimate

$$\begin{split} \mathbb{E}[\Delta_{s}((1-r)B_{2}^{n},P_{N})] &= \\ \int_{\partial B_{2}^{n}} \cdots \int_{\partial B_{2}^{n}} \left| \partial((1-r)B_{2}^{n} \cup [x_{1},\ldots,x_{N}]) \right| - \\ \left| \partial((1-r)B_{2}^{n} \cap [x_{1},\ldots,x_{N}]) \right| d\mathbb{P}(x_{1}) \dots d\mathbb{P}(x_{N}) \\ &= \mathbb{E}\left(\left| \partial((1-r)B_{2}^{n}) \cap P_{N}^{C} \right| \right) - \mathbb{E}\left(\left| (1-r)B_{2}^{n} \cap \partial P_{N} \right| \right) \\ &+ \mathbb{E}\left(\left| \left((1-r)B_{2}^{n} \right)^{C} \cap \partial P_{N} \right| \right) - \mathbb{E}\left(\left| \partial\left((1-r)B_{2}^{n} \right) \cap P_{N} \right| \right) \end{split}$$

<□ > < @ > < E > < E > E のQ @

We want to estimate

$$\mathbb{E}[\Delta_{s}((1-r)B_{2}^{n},P_{N})] = \int_{\partial B_{2}^{n}} \cdots \int_{\partial B_{2}^{n}} \left| \partial((1-r)B_{2}^{n} \cup [x_{1},\ldots,x_{N}]) \right| - \left| \partial((1-r)B_{2}^{n} \cap [x_{1},\ldots,x_{N}]) \right| d\mathbb{P}(x_{1})\ldots d\mathbb{P}(x_{N}) \\ = \mathbb{E}\left(\left| \partial((1-r)B_{2}^{n}) \cap P_{N}^{C} \right| \right) - \mathbb{E}\left(\left| (1-r)B_{2}^{n} \cap \partial P_{N} \right| \right) \\ + \mathbb{E}\left(\left| \left((1-r)B_{2}^{n} \right)^{C} \cap \partial P_{N} \right| \right) - \mathbb{E}\left(\left| \partial\left((1-r)B_{2}^{n} \cap \partial P_{N} \right| \right) \right| \right) \\ \text{we choose r such that} \\ = 2\left(\mathbb{E}\left(\left| \partial\left((1-r)B_{2}^{n} \right) \cap P_{N}^{C} \right| \right) - \mathbb{E}\left(\left| (1-r)B_{2}^{n} \cap \partial P_{N} \right| \right) \right)$$

We choose r

We choose r = r(n, N) such that

$$\mathbb{E}\left(\left|\partial((1-r)B_{2}^{n})\cap P_{N}^{C}\right|\right) - \mathbb{E}\left(\left|(1-r)B_{2}^{n}\cap\partial P_{N}\right|\right) = \\ \cdot \\ \mathbb{E}\left(\left|\left((1-r)B_{2}^{n}\right)^{C}\cap\partial P_{N}\right|\right) - \mathbb{E}\left(\left|\partial\left((1-r)B_{2}^{n}\right)\cap P_{N}\right|\right)$$

<□ > < @ > < E > < E > E のQ @

We choose r = r(n, N) such that

$$\mathbb{E}\left(\left|\partial((1-r)B_{2}^{n})\cap P_{N}^{C}\right|\right) - \mathbb{E}\left(\left|(1-r)B_{2}^{n}\cap\partial P_{N}\right|\right) = \\ \cdot \\ \mathbb{E}\left(\left|\left((1-r)B_{2}^{n}\right)^{C}\cap\partial P_{N}\right|\right) - \mathbb{E}\left(\left|\partial\left((1-r)B_{2}^{n}\right)\cap P_{N}\right|\right)$$

which is equivalent to

$$\mathbb{E}\left(\left|\partial((1-r)B_2^n) \cap P_N^C\right|\right) + \mathbb{E}\left(\left|\partial((1-r)B_2^n) \cap P_N\right|\right) = \\\mathbb{E}\left(\left|\left((1-r)B_2^n\right)^C \cap \partial P_N\right|\right) + \mathbb{E}\left(\left|(1-r)B_2^n \cap \partial P_N\right|\right)$$

We choose r = r(n, N) such that

$$\mathbb{E}\left(\left|\partial((1-r)B_{2}^{n})\cap P_{N}^{C}\right|\right) - \mathbb{E}\left(\left|(1-r)B_{2}^{n}\cap\partial P_{N}\right|\right) = \\ \cdot \\ \mathbb{E}\left(\left|\left((1-r)B_{2}^{n}\right)^{C}\cap\partial P_{N}\right|\right) - \mathbb{E}\left(\left|\partial\left((1-r)B_{2}^{n}\right)\cap P_{N}\right|\right)$$

which is equivalent to

$$\mathbb{E}\left(\left|\partial((1-r)B_{2}^{n})\cap P_{N}^{C}\right|\right)+\mathbb{E}\left(\left|\partial((1-r)B_{2}^{n})\cap P_{N}\right|\right)=\\\mathbb{E}\left(\left|\left((1-r)B_{2}^{n}\right)^{C}\cap\partial P_{N}\right|\right)+\mathbb{E}\left(\left|(1-r)B_{2}^{n}\cap\partial P_{N}\right|\right)$$

or

$$\left|\partial\left((1-r)B_{2}^{n}\right)\right|=\mathbb{E}\left(\left|\partial P_{N}\right|\right)$$

$$\left|\partial\left((1-r)B_{2}^{n}
ight)\right|=\mathbb{E}\left(\left|\partial P_{N}
ight|
ight)$$

◆□ ▶ ◆□ ▶ ◆三 ▶ ◆□ ▶ ◆□ ▶

or

$$\left|\partial\left(B_{2}^{n}
ight)\right|-\left|\partial\left((1-r)B_{2}^{n}
ight)\right| \sim$$

$$\left|\partial\left((1-r)B_{2}^{n}
ight)\right|=\mathbb{E}\left(\left|\partial P_{N}
ight|
ight)$$

or

$$\begin{aligned} \left| \partial \left(B_{2}^{n} \right) \right| &- \left| \partial \left((1-r) B_{2}^{n} \right) \right| &\sim n r \left| \partial \left(B_{2}^{n} \right) \right| \\ &= \left| \partial \left(B_{2}^{n} \right) \right| - \mathbb{E} \left(\left| \partial P_{N} \right| \right) \end{aligned}$$

▲□▶▲圖▶▲≣▶▲≣▶ ≣ のみの

$$\left|\partial\left((1-r)B_{2}^{n}
ight)\right|=\mathbb{E}\left(\left|\partial P_{N}
ight|
ight)$$

or

$$\begin{aligned} \left| \partial \left(B_{2}^{n} \right) \right| &- \left| \partial \left((1-r) B_{2}^{n} \right) \right| &\sim n r \left| \partial \left(B_{2}^{n} \right) \right| \\ &= \left| \partial \left(B_{2}^{n} \right) \right| - \mathbb{E} \left(\left| \partial P_{N} \right| \right) \end{aligned}$$

J. Müller implies for N large enough

$$\left|\partial\left(B_{2}^{n}\right)\right|-\mathbb{E}\left(\left|\partial P_{N}\right|\right)\sim n \frac{\left|\partial\left(B_{2}^{n}\right)\right|}{N^{\frac{2}{n-1}}}$$

$$\left|\partial\left((1-r)B_{2}^{n}
ight)\right|=\mathbb{E}\left(\left|\partial P_{N}
ight|
ight)$$

or

$$\begin{aligned} \left| \partial \left(B_{2}^{n} \right) \right| &- \left| \partial \left((1-r) B_{2}^{n} \right) \right| &\sim n r \left| \partial \left(B_{2}^{n} \right) \right| \\ &= \left| \partial \left(B_{2}^{n} \right) \right| - \mathbb{E} \left(\left| \partial P_{N} \right| \right) \end{aligned}$$

J. Müller implies for N large enough

$$\left|\partial\left(B_{2}^{n}\right)\right|-\mathbb{E}\left(\left|\partial P_{N}\right|\right)\sim n \frac{\left|\partial\left(B_{2}^{n}\right)\right|}{N^{\frac{2}{n-1}}}$$

$$r \sim \frac{1}{N^{\frac{2}{n-1}}}$$

$$\mathbb{E}[\Delta_{s}((1-r)B_{2}^{n},P_{N})] =$$

$$= 2\left(\mathbb{E}\left(\left|\partial\left((1-r)B_{2}^{n}\right)\cap P_{N}^{C}\right|\right) - \mathbb{E}\left(\left|(1-r)B_{2}^{n}\cap\partial P_{N}\right)\right|\right)\right)$$

$$= 2\left(I_{1}-I_{2}\right)$$

◆□ ▶ ◆□ ▶ ◆三 ▶ ◆□ ▶ ◆□ ▶

First consider

$$\begin{split} I_{1} &= \int_{\partial B_{2}^{n}} \cdots \int_{\partial B_{2}^{n}} \operatorname{vol}_{n-1} \left[\partial \left((1-r) B_{2}^{n} \right) \cap P_{N}^{c} \right] \mathbb{1}_{\{0 \in \mathsf{int}(P_{N})\}} d\mathbb{P}(x) \\ &+ \int_{\partial B_{2}^{n}} \cdots \int_{\partial B_{2}^{n}} \operatorname{vol}_{n-1} \left[\partial \left((1-r) B_{2}^{n} \right) \cap P_{N}^{c} \right] \cdot \mathbb{1}_{\{0 \notin \mathsf{int}(P_{N})\}} d\mathbb{P}(x) \end{split}$$

First consider

$$\begin{split} I_{1} &= \int_{\partial B_{2}^{n}} \cdots \int_{\partial B_{2}^{n}} \operatorname{vol}_{n-1} \left[\partial \left((1-r) B_{2}^{n} \right) \cap P_{N}^{c} \right] \mathbb{1}_{\{0 \in \mathsf{int}(P_{N})\}} d\mathbb{P}(x) \\ &+ \int_{\partial B_{2}^{n}} \cdots \int_{\partial B_{2}^{n}} \operatorname{vol}_{n-1} \left[\partial \left((1-r) B_{2}^{n} \right) \cap P_{N}^{c} \right] \cdot \mathbb{1}_{\{0 \notin \mathsf{int}(P_{N})\}} d\mathbb{P}(x) \\ &\leq \int_{\partial B_{2}^{n}} \cdots \int_{\partial B_{2}^{n}} \operatorname{vol}_{n-1} \left[\partial \left((1-r) B_{2}^{n} \right) \cap P_{N}^{c} \right] \mathbb{1}_{\{0 \in \mathsf{int}(P_{N})\}} d\mathbb{P}(x) \\ &+ \operatorname{vol}_{n-1}(\partial B_{2}^{n}) \mathbb{P}(0 \notin \mathsf{int}(P_{N})) \end{split}$$

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

where $d\mathbb{P}(x) = d\mathbb{P}(x_1) \cdots d\mathbb{P}(x_N)$

By a result of Wendel, the second summand equals

$$\begin{split} \operatorname{vol}_{n-1}(\partial B_2^n) \, \mathbb{P}(0 \not\in \mathsf{int}(P_N)) &= \operatorname{vol}_{n-1}\left(\partial B_2^n\right) 2^{-N+1} \sum_{k=0}^{n-1} \binom{N-1}{k} \\ &\leq \operatorname{vol}_{n-1}\left(\partial B_2^n\right) 2^{-N+1} n N^n. \end{split}$$

By a result of Wendel, the second summand equals

$$\begin{split} \operatorname{vol}_{n-1}(\partial B_2^n) \, \mathbb{P}(0 \not\in \mathsf{int}(P_N)) &= \operatorname{vol}_{n-1}\left(\partial B_2^n\right) 2^{-N+1} \sum_{k=0}^{n-1} \binom{N-1}{k} \\ &\leq \operatorname{vol}_{n-1}\left(\partial B_2^n\right) 2^{-N+1} n N^n. \end{split}$$

The second summand is essentially of the order 2^{-N} , and it turns out that the first summand is of the order of $N^{-\frac{2}{n-1}}$. Therefore, we can concentrate on the first summand

$$\int_{\partial B_2^n} \cdots \int_{\partial B_2^n} \operatorname{vol}_{n-1} \left[\partial \left((1-r) B_2^n \right) \cap P_N^c \right] \mathbb{1}_{\{0 \in \mathsf{int}(P_N)\}} d\mathbb{P}(x)$$