

# Math 290-1 Class 13

Friday 26th October 2018

## Eliminating redundancy

If a list of vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_r$  is linearly dependent, then we might wish to remove the ‘redundant’ vectors until we have a linearly independent set. The resulting list is then a basis of  $\text{span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_r)$ . (You might want to think about why this is true.)

There is a simple procedure for doing this: define

$$A = \begin{pmatrix} \vdots & \vdots & & \vdots \\ \vec{v}_1 & \vec{v}_2 & \cdots & \vec{v}_r \\ \vdots & \vdots & & \vdots \end{pmatrix}$$

and then put  $A$  in row-echelon form (reduced or otherwise). If column  $i$  has a pivot, then keep  $\vec{v}_i$ ; if not, then remove it from the list.

This technique is useful for finding the basis of the image of a linear transformation  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ : first find the matrix  $A$  of  $T$ , then put  $A$  in (r)ref, and then select the columns of  $A$  (not of  $\text{rref}(A)$ !) which correspond to the pivots.

## Characterising linear independence

Let  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_r$  be a list of  $n$ -dimensional vectors, and let  $A$  be the  $n \times r$  matrix whose  $i^{\text{th}}$  column is  $\vec{v}_i$  for all  $1 \leq i \leq r$  (just like we did above). The following statements are equivalent to saying that the vectors  $\vec{v}_1, \dots, \vec{v}_r$  are linearly independent:

- If  $k_1\vec{v}_1 + k_2\vec{v}_2 + \dots + k_r\vec{v}_r = \vec{0}$ , then  $k_1 = k_2 = \dots = k_r = 0$ ;
- No  $\vec{v}_i$  can be expressed as a linear combination of the other vectors  $\vec{v}_j$  (for  $j \neq i$ );
- The only solution to  $A\vec{x} = \vec{0}$  is  $\vec{x} = \vec{0}$ ;
- $\ker(A) = \{\vec{0}\}$ ;
- $\text{rank}(A) = r$ .

## Coordinates

Vectors  $\vec{v}_1, \dots, \vec{v}_r$  are a basis of a subspace  $V$  if they span  $V$  and are linearly independent—in this case, each vector  $\vec{v}$  in  $V$  can be expressed *uniquely* as  $c_1\vec{v}_1 + \dots + c_r\vec{v}_r$  for some scalars  $c_1, \dots, c_r$ . We will soon refer to the numbers  $c_1, \dots, c_r$  as the *coordinates* of  $\vec{v}$  with respect to the basis  $\vec{v}_1, \dots, \vec{v}_r$ .

*We will focus on the exercises from Wednesday. If there's time, we might get to this one—if not, see Canvas for the worked solution!*

1. Find a basis for the subspace of  $\mathbb{R}^5$  consisting of all linear combinations of the following vectors:

$$\begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 7 \\ -2 \\ -7 \\ -2 \\ -1 \end{pmatrix}, \begin{pmatrix} -2 \\ 2 \\ 2 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 7 \\ 2 \\ -1 \\ -4 \\ -5 \end{pmatrix}, \begin{pmatrix} 0 \\ 2 \\ -2 \\ 4 \\ 3 \end{pmatrix}$$