

1. Determine whether each of the following statements is **TRUE** or **FALSE**. Justify your answer. (This problem has **four** parts.)

- (a) If  $A$  is any square matrix and  $q(\mathbf{x}) = \mathbf{x} \cdot A\mathbf{x}$  is a quadratic form, then  $A$  must be diagonalizable.

Answer: **FALSE**

$$\text{Counterexample: } q(x,y) = \begin{bmatrix} x \\ y \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \\ = \begin{bmatrix} x \\ y \end{bmatrix} \cdot \begin{bmatrix} x+y \\ y \end{bmatrix} = x^2 + xy + y^2$$

is a quadratic form, but

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \text{ is not diagonalizable.}$$

- (b) If  $A$  is a symmetric matrix and  $\mathbf{v}$  and  $\mathbf{w}$  are vectors with  $\mathbf{v}$  in the kernel of  $A$  and  $\mathbf{w}$  in the image of  $A$ , then  $\mathbf{v} \cdot \mathbf{w} = 0$ .

Answer: **TRUE**

Since  $\vec{w}$  is in the image of  $A$ ,  $\vec{w} = A\vec{x}$  for some  $\vec{x}$ .

$$\text{So } \vec{v} \cdot \vec{w} = \vec{v} \cdot (A\vec{x}) = (A^T \vec{v}) \cdot \vec{w} = (A\vec{v}) \cdot \vec{w} \quad \begin{array}{l} \text{since } A \text{ is} \\ \text{symmetric} \end{array} \\ = \vec{0} \cdot \vec{w} = 0. \\ \text{since } \vec{v} \in \ker A.$$

Alternatively, we know  $\ker(A^T) = (\text{im } A)^\perp$ , so

$$\begin{aligned} & \vec{v} \in \ker(A) \\ \Rightarrow & \vec{v} \in \ker(A^T) \quad \text{since } A \text{ is symmetric} \\ \Rightarrow & \vec{v} \in (\text{im } A)^\perp \\ \Rightarrow & \vec{v} \cdot \vec{w} = 0 \text{ for all } \vec{w} \in \text{im } A, \text{ as desired.} \end{aligned}$$

(c) If  $\mathbf{a}, \mathbf{b}, \mathbf{c}$  are any nonzero vectors in  $\mathbb{R}^3$ , then  $(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c} = (\mathbf{c} \times \mathbf{b}) \cdot \mathbf{a}$ .

Answer: FALSE

Let  $\vec{a} = \vec{e}_1$ ,  $\vec{b} = \vec{e}_2$  and  $\vec{c} = \vec{e}_3$ .

$$\text{Then } (\vec{a} \times \vec{b}) \cdot \vec{c} = (\vec{e}_1 \times \vec{e}_2) \cdot \vec{e}_3 = \vec{e}_3 \cdot \vec{e}_3 = 1.$$

$$(\vec{c} \times \vec{b}) \cdot \vec{a} = (\vec{e}_3 \times \vec{e}_2) \cdot \vec{e}_1 = -\vec{e}_1 \cdot \vec{e}_1 = -1.$$

$$\text{So, } (\vec{e}_1 \times \vec{e}_2) \cdot \vec{e}_3 \neq (\vec{e}_3 \times \vec{e}_2) \cdot \vec{e}_1$$

(d) If  $V$  is a nonzero subspace of  $\mathbb{R}^n$ , then  $V$  has an orthonormal basis.

Answer: TRUE

Let  $V$  be a nonzero subspace of  $\mathbb{R}^n$ . There exists a basis  $\{\vec{v}_1, \dots, \vec{v}_m\}$  for  $V$ . Applying the Gram-Schmidt process to  $\vec{v}_1, \dots, \vec{v}_m$ , we obtain an orthonormal set  $\{\vec{u}_1, \dots, \vec{u}_m\}$  such that

$$\text{span}\{\vec{u}_1, \dots, \vec{u}_m\} = \text{span}\{\vec{v}_1, \dots, \vec{v}_m\} = V.$$

Each orthonormal set is linearly independent. Therefore,  $\{\vec{u}_1, \dots, \vec{u}_m\}$  is an orthonormal basis for  $V$ .

2. Determine whether each of the following statements is **ALWAYS** true, **SOMETIMES** true, or **NEVER** true. Justify your answer. (This problem has **four** parts.)

(a) Suppose that  $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  is an orthonormal set of vectors in  $\mathbb{R}^n$ . Then

$$\{\mathbf{u}_1 - \mathbf{u}_2, \mathbf{u}_2 - \mathbf{u}_3, \mathbf{u}_1 - \mathbf{u}_3\}$$

is also an orthonormal set.

Answer: **NEVER**

Note that  $\|\hat{\mathbf{u}}_1 - \hat{\mathbf{u}}_2\|^2 = (\hat{\mathbf{u}}_1 - \hat{\mathbf{u}}_2) \cdot (\hat{\mathbf{u}}_1 - \hat{\mathbf{u}}_2) = \|\hat{\mathbf{u}}_1\|^2 + \|\hat{\mathbf{u}}_2\|^2 = 2$ ,  
so the vectors do not have length 1.

(b) For a square matrix  $Q$  whose columns are perpendicular to one another,  $Q^T Q = I$ .

Answer: **SOMETIMES**

Example:  $Q = I$ , so  $Q^T Q = I I = I$

Counterexample:  $Q = 0$ , so  $Q^T Q = 0 0 = 0 \neq I$

- (c) For an  $n \times m$  matrix  $A$  and a vector  $\mathbf{b}$  in  $\mathbb{R}^n$ , there is a vector  $\mathbf{x}$  in  $\mathbb{R}^m$  such that  $A\mathbf{x} = \text{proj}_{\text{im}A} \mathbf{b}$ .

Answer: **ALWAYS**

$\text{proj}_{\text{im}A} \vec{b}$  is in  $\text{im}A$ , and anything in the image of  $A$  can be written as  $A\vec{x}$  for some  $\vec{x}$

or the solution of  $A^T A \vec{x} = A^T \vec{b}$ , which always exists, satisfies  $A\vec{x} = \text{proj}_{\text{im}A} \vec{b}$

- (d) For a number  $k$ , the line with parametric equations

$$x = 4 - 2t, \quad y = k + t, \quad z = 2k - 1$$

intersects the surface described by the equation  $(x - 4)^2 + (y - k)^2 + (z + 1)^2 = 1$ .

Answer: **SOMETIMES**

Plugging in  $(x, y, z)$  values:

$$\underbrace{(-2t)^2}_{x-4} + \underbrace{(t)^2}_{y-k} + \underbrace{(2k)^2}_{z+1} = 1 \quad \text{becomes}$$

$$5t^2 = 1 - 4k^2 \quad \text{or} \quad t^2 = \frac{1 - 4k^2}{5}$$

This has solution for  $t$  when  $k=0$   
but not when  $k = \pm 10$

3. At O'Hare airport, the average low temperature (in degrees Celsius)  $t$  months into the year is listed below:

$t$	$^{\circ}\text{C}$
0	-8
3	5
6	20
9	8

Find the function of the form  $f(t) = c_0 + c_1 \sin(\frac{\pi}{6}t) + c_2 \cos(\frac{\pi}{6}t)$  which best fits the data above, using least squares.

$$f(0) = c_0 + c_2 = -8$$

$$f(3) = c_0 + c_1 = 5$$

$$f(6) = c_0 - c_2 = 20$$

$$f(9) = c_0 - c_1 = 8$$

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$(A^T A)^{-1} A^T b = \begin{bmatrix} \frac{1}{4} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} -8 \\ 5 \\ 20 \\ 8 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{4} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 25 \\ -25 \\ -3 \\ -28 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{25}{4} \\ -\frac{3}{2} \\ -14 \end{bmatrix}$$

$$\text{So } f(t) = \frac{25}{4} - \frac{3}{2} \sin\left(\frac{\pi}{6}t\right) - 14 \cos\left(\frac{\pi}{6}t\right)$$

4. (This problem has **three** parts.) Define the quadratic form  $q : \mathbb{R}^2 \rightarrow \mathbb{R}$  by

$$q(x, y) = 4x^2 + 4xy + 7y^2.$$

(a) Determine whether  $q$  is positive definite, negative definite, or indefinite.

$$A = \begin{bmatrix} 4 & 2 \\ 2 & 7 \end{bmatrix}$$

$$\begin{aligned} \det(A - xI) &= \det \begin{pmatrix} 4-x & 2 \\ 2 & 7-x \end{pmatrix} \\ &= (x-4)(x-7) - 4 \\ &= x^2 - 11x + 28 - 4 \\ &= x^2 - 11x + 24 \\ &= (x-8)(x-3) \end{aligned}$$

$$x = 8, 3$$

positive definite as all eigenvalues  $> 0$ .

(b) Find a set of principal axes for  $q$ .

$$E_3: \begin{bmatrix} 1 & 2 & | & 0 \\ 2 & 4 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$x = -2y$$

$$\text{get } \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

$$E_8: \begin{bmatrix} -4 & 2 & | & 0 \\ 2 & -1 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

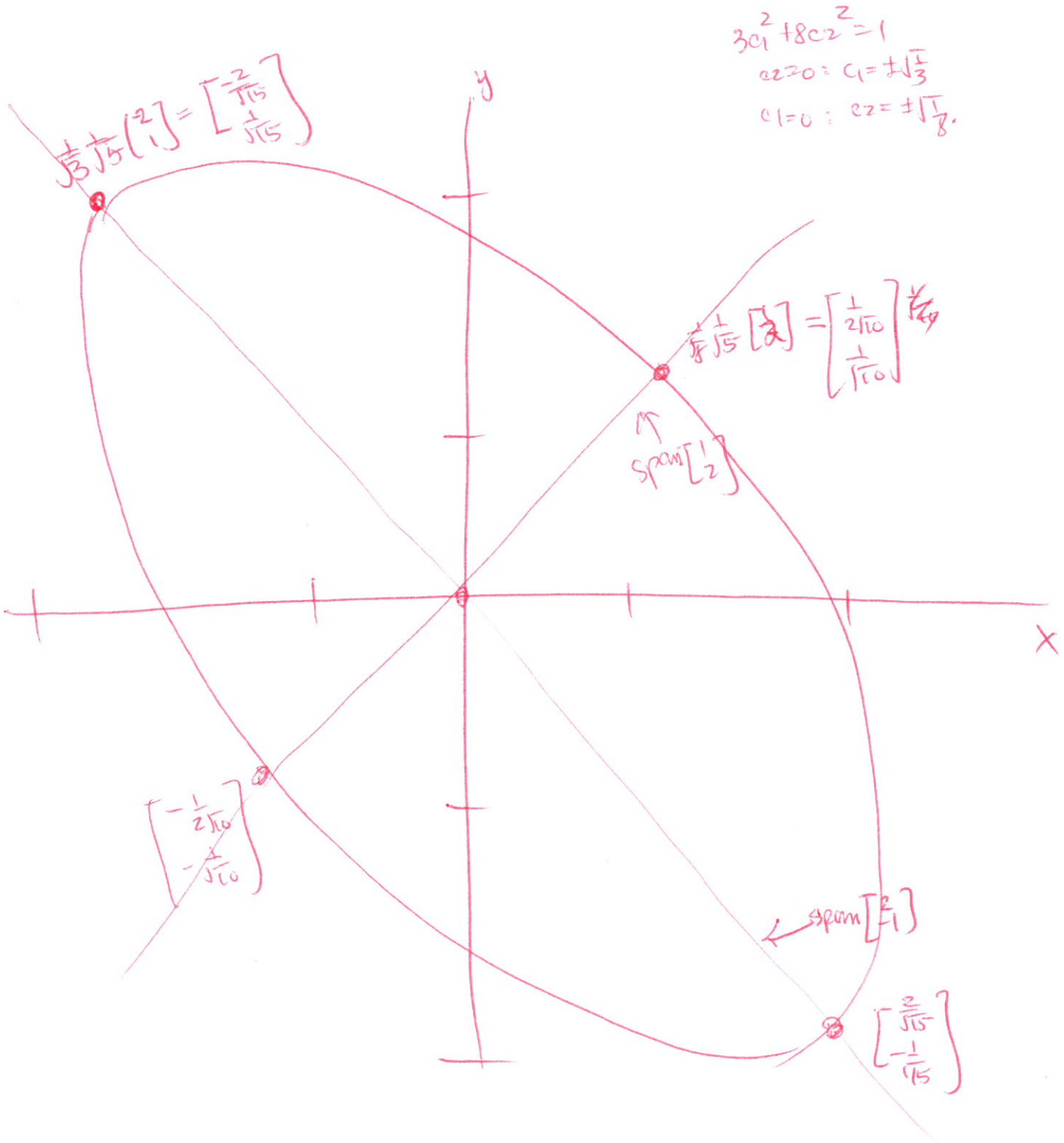
$$2x = y$$

$$\text{get } \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

So principal axes

$$\text{span} \begin{bmatrix} -2 \\ 1 \end{bmatrix} \text{ \& \; } \text{span} \begin{bmatrix} 1 \\ 2 \end{bmatrix}.$$

(c) Draw the curve whose equation is  $4x^2 + 4xy + 7y^2 = 1$ , labeling the principal axes and the intercepts of the curve with these axes. The intercepts should be labeled by their standard  $(x, y)$  coordinates.





5. Let  $P$  be the plane  $x + 2y + 4z = 0$  and let  $\vec{x} = \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix}$ . Find the distance from  $\vec{x}$  to  $P$ .

Method 1 distance =  $\| \text{proj}_{\vec{n}} \vec{x} \|$  where  $\vec{n} = \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}$  is normal vector

$$\text{proj}_{\vec{n}} \vec{x} = \left( \frac{\vec{x} \cdot \vec{n}}{\vec{n} \cdot \vec{n}} \right) \vec{n} = \frac{12}{21} \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}.$$

$$\text{distance} = \left\| \frac{12}{21} \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix} \right\| = \frac{12}{21} \sqrt{21}$$

Method 2 plane =  $\text{Span} \left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -4 \\ 0 \\ 1 \end{pmatrix} \right\}$

$$\text{Set } A = \begin{pmatrix} -2 & -4 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \vec{x} = \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix}.$$

$$\text{Solve } A^T A \vec{y} = A^T \vec{x} \rightarrow \begin{pmatrix} 5 & 8 \\ 8 & 17 \end{pmatrix} \vec{y} = \begin{pmatrix} -5 \\ -5 \end{pmatrix}$$

$$\rightarrow \vec{y} = \begin{pmatrix} -15/7 \\ 5/7 \end{pmatrix}$$

$$\text{Then } \text{proj}_P \vec{x} = A \vec{y} = \begin{pmatrix} 10/7 \\ -15/7 \\ 5/7 \end{pmatrix}$$

$$\text{and distance} = \left\| \vec{x} - \text{proj}_P \vec{x} \right\| = \frac{4\sqrt{21}}{7}$$

Same



6. (This problem has **two** parts.) Suppose that  $A$  is a  $4 \times 4$  matrix with eigenvalues 2 and  $-1$ , and associated eigenvectors

$$\begin{matrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 0 \\ -2 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \\ 2 \\ 1 \end{bmatrix} \text{ for } 2 \text{ and } \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix} \text{ for } -1. \\ v_1 \quad v_2 \quad v_3 \qquad \qquad \qquad v_4 \end{matrix}$$

- (a) Find a basis of  $\mathbb{R}^4$  consisting of orthonormal eigenvectors of  $A$ .

Apply GS to  $\{v_1, v_2, v_3\}$ :

orthogonalize:  $w_1 = v_1$

$$w_2 = \begin{pmatrix} -2 \\ 0 \\ 0 \\ -2 \end{pmatrix} - \frac{-4}{4} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ -1 \\ -1 \end{pmatrix}$$

$$w_3 = \begin{pmatrix} 1 \\ 4 \\ 2 \\ 1 \end{pmatrix} - \frac{8}{4} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} - \frac{4}{4} \begin{pmatrix} -1 \\ -1 \\ -1 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \\ -1 \\ 0 \end{pmatrix}$$

normalize:

$$u_1 = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \quad u_2 = \frac{1}{2} \begin{pmatrix} -1 \\ -1 \\ -1 \\ -1 \end{pmatrix}, \quad u_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ -1 \\ -1 \\ 0 \end{pmatrix}$$

$$u_4 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 0 \\ -1 \end{pmatrix}$$

$v_4$  is already  $\perp$  to  $v_1, v_2, v_3$ .

(b) Compute  $A^3 \begin{bmatrix} 1 \\ 2 \\ -1 \\ 1 \end{bmatrix}$  explicitly.

$$\begin{pmatrix} 1 \\ 2 \\ -1 \\ 1 \end{pmatrix} = 3 \cdot \frac{1}{4} \underbrace{\begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}}_{w_1} - 1 \cdot \frac{1}{4} \underbrace{\begin{pmatrix} 1 \\ -1 \\ 1 \\ 1 \end{pmatrix}}_{w_2} + 3 \cdot \frac{1}{2} \underbrace{\begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix}}_{w_3} + 0 \cdot \frac{1}{2} \underbrace{\begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}}_{w_4}$$

$$\begin{aligned} A^3 \begin{pmatrix} 1 \\ 2 \\ -1 \\ 1 \end{pmatrix} &= \frac{3}{4} A^3 w_1 - \frac{1}{4} A^3 w_2 + \frac{3}{2} A^3 w_3 \\ &= \frac{3}{4} \cdot 2^3 w_1 - \frac{1}{4} \cdot 2^3 w_2 + \frac{3}{2} \cdot 2^3 w_3 \end{aligned}$$

$$\begin{aligned} &= 2^3 \cdot \begin{pmatrix} 1 \\ 2 \\ -1 \\ 1 \end{pmatrix} \\ &= \boxed{\begin{pmatrix} 8 \\ 16 \\ -8 \\ 8 \end{pmatrix}} \end{aligned}$$